

MOTOR VEHICLE HAVING AN OCCUPANT PROTECTION SYSTEM

FIELD OF THE INVENTION

The present invention relates to a motor vehicle having an occupant protection system or an occupant protection device, such as an airbag.

BACKGROUND INFORMATION

Airbag systems are described, for example, in the article "Hardware and Mechanics of Real Airbag Control Systems" published on the Internet page www.informatik.uni-dortmund.de/airbag/seminarphase/hardware_vortrag.pdf.

U.S. Patent No. 5,583,771, U.S. Patent No. 5,684,701, and U.S. Patent No. 6,532,508 [[B1]] describe the triggering of an airbag by a neural network as a function of an output signal of an acceleration sensor.

[[DE]] German Published Patent Application No. 198 54 380

[[A1]] describes a method for detecting the severity of a vehicle collision, where the output signals of a plurality of acceleration sensors are supplied to a neural network. In the method, the start of the evaluation of the acceleration-sensor output signals is determined by a trigger signal, which is output by an acceleration sensor when its output signal exceeds a predefined threshold value. This acceleration sensor causes the other acceleration sensors to supply the respective output signal at one and the same time. It is also provided that the output signals of the acceleration sensors be integrated one or two times.

[[DE]] German Published Patent Application No. 100 35 505

[[A1]] describes a method, in which the future time characteristic of the output signal of an acceleration sensor

is predicted with the aid of a neural network on the basis of the acceleration-sensor signals at at least one defined time.

[[DE]] German Published Patent Application No. 100 40 111

5 [[A1]] describes a method for producing a triggering decision for restraining devices in a vehicle, where the difference of measured acceleration values is calculated and the magnitude of the difference is subsequently integrated. The integral is compared to at least one threshold value. If the integral
10 does not exceed this threshold value by a predefined time, then the position of a triggering threshold for the measured acceleration or for a speed change derived from it is modified in such a manner, that the triggering sensitivity becomes lower.

15 Described in [[DE]] German Published Patent Application No. 101 03 661 [[C1]] is a method for sensing lateral impact in a motor vehicle; acceleration sensors, from whose output signals the difference is calculated, being situated on the left and
20 right sides of the vehicle. The differential acceleration signal is integrated or summed up. For the purpose of side-impact sensing, the differential speed signal is compared to a threshold value, which is calculated as a function of the differential acceleration signal.

25 SUMMARY
The ~~object~~ Example embodiments of the present invention ~~is to~~ may provide a motor vehicle that [[is]] may be improved with regard to occupant protection.

30 The ~~above mentioned object~~ is achieved by a A motor vehicle having may include at least one first crash sensor ~~situated~~ arranged in a safety zone of the motor vehicle, for measuring a motion variable of the motor vehicle, and having may include
35 at least one second crash sensor ~~situated~~ arranged in a crash

zone of the motor vehicle, for measuring a (further) or the same motion variable of the motor vehicle; ~~the~~. The motor vehicle ~~including~~ may include an occupant detection device controllable via an ignition signal, and a control unit for
5 ascertaining the ignition signal as a function of the measured motion variables and/or, in each instance, as a function of a time average of the measured motion variables over at least one time interval.

10 A crash zone of the motor vehicle within the ~~meaning of the present invention is~~ present context may include, in particular e.g., a region of the motor vehicle which, in the event of a collision of the motor vehicle with an obstacle, can may be destroyed prior to a (setpoint) triggering time of
15 the occupant protection device. A safety zone of the motor vehicle within the ~~meaning of the present invention is~~, in particular present context may include, e.g., a region of the motor vehicle which, in the event of a collision of the motor vehicle with an obstacle, is not destroyed or is destroyed
20 after a (setpoint) triggering time of the occupant protection device.

An occupant protection device within the ~~meaning of the present invention is~~, in particular present context may
25 include, e.g., an airbag and/or a belt tensioner. A motion variable of the motor vehicle within the ~~meaning of the present invention~~ present context may be an acceleration, a speed, or a displacement, or a variable derived from these variables.

30 A crash sensor within the ~~meaning of the present invention~~ present context may be an acceleration sensor for measuring an acceleration in one or more directions. A crash sensor within the ~~meaning of the present invention~~ present context may also
35 be a radar device, an infrared set-up, or a camera. In this

case, a motion variable of the motor vehicle may be a distance of the motor vehicle from an obstacle, the first or second derivative of this distance, or another equivalent similar variable. A crash sensor within the ~~meaning of the present invention~~ present context may also be a sensor for measuring a deformation of the motor vehicle. Such a sensor may be a fiber-optic sensor or a sensor described in ~~[[DE]]~~ German Published Patent Application No. 100 16 142 [[Al]]. In this case, a motion variable of the motor vehicle may be a deformation of the motor vehicle, the first or second derivative of this deformation, or another equivalent similar variable.

A time average within the ~~meaning of the present invention~~ present context may be an arithmetic mean or a weighted average. In the case of such a weighted average, e.g., more recent values of the motion variable in the relevant time interval may be more heavily weighted than older values of the motion variable in the relevant time interval. An average value within the ~~meaning of the present invention~~ present context may also be a value proportional to an average value. ~~In an advantageous refinement of the present invention, the~~ The average value ~~[[is]]~~ may be a value proportional to the arithmetic mean. In this context, the average value ~~is~~ advantageously may be a value proportional to the integral of the motion variable in the relevant time interval or a value proportional to the sum of sampled values of the motion variable in the relevant time interval.

An ignition signal within the ~~meaning of the present invention~~ present context may be a binary signal, which indicates if an occupant protection device, such as an airbag and/or a belt tensioner, should be triggered. Such an ignition signal within the ~~meaning of the present invention~~ present context may be a "FIRE/NO-FIRE" signal described in ~~[[DE]]~~ German

Published Patent Application No. 100 35 505 [[A1]]. An

ignition signal within the ~~meaning of the present invention~~

present context may also be a more complex signal, which

indicates the degree (e.g., stage 1 or stage 2) to which an

airbag should be fired. In addition, such an ignition signal

within the ~~meaning of the present invention~~ present context

may be a crash-severity parameter or an occupant acceleration

or loading described in [[DE]] German Published Patent

Application No. 100 35 505 [[A1]]. An ignition signal within

the ~~meaning of the present invention~~ present context may be,

or include, an information item indicating the location and/or

the direction of a collision.

~~In an advantageous refinement of the present invention, the~~

The first crash sensor and the second crash sensor are

situated may be arranged at least 0.5 m away from each other.

~~In a further advantageous refinement of the present invention,~~

~~the~~ The first crash sensor ~~[[is]]~~ may be connected to the

control unit, integrated into the control unit, or situated

arranged in a housing with the control unit.

~~In a further advantageous refinement of the present invention,~~

~~the~~ The control unit ~~includes~~ may include

- at least one first triggering relationship for
ascertaining the ignition signal as a function of
the measured motion variables and/or, in each
instance, as a function of a time average of the
measured motion variables over the at least first
time interval; and/or

- at least one second triggering relationship for
ascertaining the ignition signal as a function of
the motion variable measured by the first crash
sensor and/or as a function of its time average over
the at least first time interval, but not as a
function of the motion variable measured by the

second crash sensor and/or not as a function of its
time average over the at least first time interval.

~~In a further advantageous refinement of the present invention,~~
5 the The control unit ~~includes~~ may include a selection module
for selecting the first triggering relationship or the second
triggering relationship for instantaneously ascertaining the
ignition signal, the selection between the second triggering
relationship and the first triggering relationship being made,
10 ~~in particular e.g.,~~ as a function of the motion variable
measured by the second crash sensor and/or as a function of
its time average over the at least first time interval.

~~In a further advantageous refinement of the present invention,~~
15 the The ignition signal ~~[[is]]~~ may also be ascertainable as a
function of a time average of the motion variable measured by
the first crash sensor, over a second time interval that is
different from the first time interval. Within the ~~meaning of~~
~~the present invention~~ present context, a second time interval
20 different from a first time interval may differ from the first
time interval in its length and/or its position.

~~In a further advantageous refinement of the present invention,~~
the The first time interval and/or the second time interval
25 ~~[[is]]~~ may be between 1 ms and 200 ms long, ~~in particular~~
e.g., between 4 ms and 32 ms long, and ~~advantageously, e.g.,~~
between 8 ms and 24 ms long.

~~In a further advantageous refinement of the present invention,~~
30 the The first time interval and/or the second time interval
are may be staggered by between 1 ms and 50 ms, and
~~advantageously, e.g.,~~ by between 2 ms and 16 ms.

~~The above mentioned object is additionally achieved by~~ In a
35 method for manufacturing a motor vehicle, ~~in particular e.g.,~~

a motor vehicle having one or more of the above-mentioned features, at least one first crash sensor for measuring a motion variable of the motor vehicle being ~~situated~~ is arranged in a safety zone of the motor vehicle, at least one second crash sensor for measuring a motion variable of the motor vehicle being ~~situated~~ is arranged in a crash zone of the motor vehicle, and an occupant detection device controllable via an ignition signal and a control unit for ascertaining the ignition signal as a function of the measured motion variables and/or, in each instance, as a function of a time average of the measured motion variables over at least one first time interval, being ~~situated~~ is arranged in the motor vehicle.

15 ~~In one advantageous refinement of the present invention,~~ The following features may be provided:

- at least one first triggering relationship for ascertaining the ignition signal as a function of the measured motion variables and/or, in each instance, as a function of a time average of the measured motion variables over the at least first time interval is generated (and, ~~in particular~~ e.g., implemented in the control unit); and/or
- at least one second triggering relationship for ascertaining the ignition signal as a function of the motion variable measured by the first crash sensor and/or as a function of its time average over the at least first time interval, but not as a function of the motion variable measured by the second crash sensor and/or not as a function of its time average over the at least first time interval, is generated (and, ~~in particular~~ e.g., implemented in the control unit).

~~In a further advantageous refinement of the present invention,~~
the **The** first triggering relationship and/or the second
triggering relationship ~~[[is]]~~ may be generated (~~in particular~~
e.g., automatically) as a plurality of comparisons of the
5 motion variables and/or their time averages over the at least
first time interval and/or over at least the first time
interval and a second time interval different from the first
time interval, to a plurality of limiting values.

10 ~~In a further advantageous refinement of the present invention,~~
the **The** limiting values are may be automatically determined,
the number of comparisons ~~[[is]]~~ may be automatically
determined, the order of the comparisons ~~[[is]]~~ may be
automatically selected, a measured motion variable and/or its
15 time average over the at least first time interval and/or over
the at least first time interval and the second time interval
~~[[is]]~~ may be automatically selected for a comparison, and/or
the age of the motion variables and/or of the time averages
over the at least first time interval and/or over the at least
20 first time interval and the second time interval ~~[[is]]~~ may be
automatically selected for the comparisons.

~~In a further advantageous refinement of the present invention,~~
the **The** first triggering relationship and/or the second
25 triggering relationship ~~[[is]]~~ may be generated as a function
of the measured motion variable or its time average over the
at least first time interval and/or over at least the first
time interval and the second time interval of a situation, for
which a setpoint triggering time of the occupant protection
30 device is known, but the measured motion variable or its time
average over the at least first time interval and/or over at
least the first time interval and the second time interval
being disregarded in a training-suppression time interval
prior to the setpoint triggering time of the occupant
35 protection device, around the setpoint triggering time of the

occupant protection device, or after the setpoint triggering time of the occupant protection device, during the generation of the first triggering relationship and/or the second triggering relationship.

5

~~In a further advantageous refinement of the present invention,~~
the **The** measured motion variable and/or its time average over the at least first time interval and/or over the at least first time interval and the second time interval ~~[[is]]~~ may be
10 disregarded in a training-suppression time interval prior to the setpoint triggering time of the occupant protection device, when the first triggering relationship and/or the second triggering relationship is generated.

15 ~~In a further advantageous refinement of the present invention,~~
the **The** training-suppression time interval ~~[[is]]~~ may be between 1 ms and 40 ms long, in particular e.g., between 2 ms and 10 ms long, and advantageously approximately, e.g., 5 ms long.

20

A motor vehicle in the ~~sense of the present invention is,~~ in particular present context may include, e.g., a land vehicle that may be used individually in road traffic. ~~In particular~~
~~However,~~ motor vehicles in the ~~sense of the present invention~~
25 present context are not restricted to land vehicles having an internal combustion engine.

Further advantages features and details are ~~derived from the following description of exemplary embodiments, objects that~~
30 ~~are identical or substantially identical being denoted by the same reference numerals.~~ The figures show: of example
embodiments of the present invention are described in more detail below with reference to the appended Figures.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a plan view of a motor vehicle[[]].

Fig. 2 illustrates an exemplary embodiment of an occupant
5 protection system[[]].

Fig. 3 illustrates an exemplary embodiment of a control
module[[]].

10 Fig. 4 illustrates an exemplary embodiment of a triggering
module[[]].

Fig. 5 illustrates an exemplary embodiment of an output signal
of a crash sensor[[]].

15 Fig. 6 illustrates the integral of the output signal [[of]]
illustrated in Fig. 5, in a time interval[[]].

Fig. 7 illustrates an exemplary embodiment of a trigger
20 generator[[]].

Fig. 8 illustrates an exemplary embodiment of a neural
network[[]].

25 Fig. 9 illustrates an exemplary embodiment of a decision
tree[[]].

Fig. 10 illustrates an exemplary embodiment of a method for
manufacturing a motor vehicle[[]].

30 Fig. 11 illustrates the integral ~~according to~~ illustrated in
Fig. 6, having a training-suppression time interval[[]].

Fig. 12 illustrates a section of the integral ~~according to~~
35 illustrated in Fig. 11[[]].

Fig. 13 illustrates a triggering information item having a training-suppression time interval[[;]].

5 Fig. 14 illustrates a section of the integral ~~according to~~
illustrated in Fig. 6[[;]].

Fig. 15 illustrates a further triggering information item having a training-suppression time interval[[;]].

10

Fig. 16 illustrates a further exemplary embodiment of a triggering module[[;]].

15 Fig. 17 illustrates a further exemplary embodiment of a triggering module~~;~~ and.

Fig. 18 illustrates a further exemplary embodiment of a triggering module.

20 DETAILED DESCRIPTION

Fig. 1 ~~shows~~ is a plan view of a motor vehicle 1 having an occupant protection system, which is ~~represented~~ illustrated in Fig. 2 in the form of a block diagram. The occupant protection system includes at least one airbag 15, ~~which is not represented in Fig. 1 but rather in~~ see Fig. 2, and/or a belt tensioner 16, ~~which is not represented in Fig. 1 but rather in~~ see Fig. 2. The occupant protection system additionally includes a control unit 2 for triggering airbag 15 and/or belt tensioner 16, as well as a crash sensor S2
25 integrated into the right front end of motor vehicle 1 and a crash sensor S3 integrated into the left front end of motor vehicle 1. Crash sensors S2 and S3 are connected to control unit 2 by leads 5 and 6.

Crash sensors S2 and S3, as well as an additional crash sensor S1 integrated into control unit 2, as ~~shown~~ **illustrated** in Fig. 2, **may** take the form of acceleration sensors ~~in the present exemplary embodiment~~. Suitable acceleration sensors are described, for example, in chapter 3.2, 'Acceleration Sensor,' of the article "Hardware and Mechanics of Real Airbag Control Systems" published on the Internet page www.informatik.uni-dortmund.de/airbag/seminarphase/hardware_vortrag.pdf.

Examples of suitable acceleration sensors include Bosch SMB060, Bosch PAS3, or Bosch UPF1. A suitable acceleration sensor may include, for example, a Bessel low-pass filter having a cutoff frequency of, e.g., 400 Hz. Crash sensors S1, S2, and S3 supply acceleration values aS1, aS2, and aS3, respectively, as output signals.

Crash sensors S2 and S3 are ~~situated~~ **arranged** in a crash zone 3, which is bounded by the outer contours of motor vehicle 1 and a dotted line designated by reference numeral 7. In this context, crash zone 3 defines a region of motor vehicle 1, which, in the event of a collision of motor vehicle 1 with an obstacle, ~~can~~ **may** be destroyed prior to a triggering time of airbag 15 and/or belt tensioner 16. Control unit 2 is ~~situated~~ **arranged** with crash sensor S1 in a safety zone 4, which is bounded by a dotted line designated by reference numeral 8. In this context, safety zone 4 defines a region of the motor vehicle, which, in the event of a collision of motor vehicle 1 with an obstacle, is not destroyed or is only destroyed after a triggering time of airbag 15 and/or belt tensioner 16. Within the ~~meaning of the present invention~~ **present context**, a collision of motor vehicle 1 with an obstacle is, ~~in particular~~ **e.g.**, a collision from whose consequences an occupant protection device, such as airbag 15 or belt tensioner 16, should protect the occupant or occupants

of motor vehicle 1. In the described exemplary embodiment, such a collision is a collision with a frontal component.

Actual crash zone 3 or actual safety zone 4 according to the
5 above-mentioned definition is a function of the individual
design or shape of the motor vehicle considered. Therefore,
crash zone 3 and safety zone 4 of motor vehicle 1 ~~cannot~~ may
not specify any universally applicable description of the
position of crash zones and safety zones within the meaning of
10 the above-mentioned definition. The position of crash zone 3
and safety zone 4 illustrated in Fig. 1 is used solely for
~~explaining the present invention~~ illustrative purposes.

The occupant protection system further includes a belt sensor
15 11 for detecting if a seat belt is being used, and for
outputting a corresponding belt information item MBELT. The
occupant protection system further includes a seat-occupancy
sensor 12 for detecting if, or how, a seat is occupied, and
for outputting a corresponding seat-occupancy information item
20 MSEAT. An example of a suitable seat-occupancy sensor is a
pressure sensor integrated into the seat. Also suitable is an
infrared scanning system described in chapter 3.3, "Interior
Sensing," of the article "Hardware and Mechanics of Real
Airbag Control Systems" published on the Internet page
25 [www.informatik.uni-](http://www.informatik.uni-dortmund.de/airbag/seminarphase/hardware_vortrag.pdf)
[dortmund.de/airbag/seminarphase/hardware_vortrag.pdf](http://www.informatik.uni-dortmund.de/airbag/seminarphase/hardware_vortrag.pdf).
Infrared scanning and fuzzy logic not only allow seat
occupancy to be detected, but also allow a determination as to
whether the seat occupant is an object, such as a purse, or a
30 person. To this end, a line of, e.g., eight or more light-
emitting diodes above the seat emit infrared light, and a CCD
matrix of 64 pixels records the scene illuminated in this
manner. These charged coupled devices, abbreviated CCD, are
made up of photodiodes and amplifier elements in matrix
35 configurations. In this context, incident light releases

charge carriers in each instance. A signal generated in this manner is amplified, processed, and stored. This procedure is repeated at different angles, and the seat is scanned in this manner. Image-processing algorithms and fuzzy-logic algorithms detect contours of objects and persons from these signals.

It may also be provided that the occupant-protection system include a control element 14 for activating or deactivating airbag 15. A corresponding switching signal is designated by reference character ONOFF.

Control unit 2 includes a control module 10 for calculating and outputting an ignition signal AIR for airbag 15 and/or an ignition signal BELT for belt tensioner 16 as a function of acceleration values aS1, aS2, and aS3, belt information item MBELT, seat-occupancy information item MSEAT, and switching signal ONOFF.

Fig. 3 ~~shows~~ illustrates an exemplary embodiment of control module 10. Control module 10 includes a triggering module 20 for calculating and outputting an ignition recommendation CRASH as a function of acceleration values aS1, aS2, and aS3. Control module 10 additionally includes a firing table 21 for calculating and outputting ignition signal AIR for airbag 15 and/or ignition signal BELT for belt tensioner 16 as a function of ignition recommendation CRASH, belt information item MBELT, seat-occupancy information item MSEAT, and/or switching signal ONOFF. Thus, it may be provided that ignition signal AIR only be equal to ignition recommendation CRASH when a corresponding seat is occupied by a person of a specific size, and that ignition signal AIR be otherwise equal to 0.

Both ignition recommendation CRASH and ignition signals AIR and BELT may be ignition signals within the ~~meaning of the~~ claims present context. Both ignition recommendation CRASH and ignition signals AIR and BELT may be a binary signal, e.g., one corresponding to the "FIRE/NO-FIRE" signal described in [[DE]] German Published Patent Application No. 100 35 505 [[A1]], the binary signal indicating whether an occupant protection device, such as an airbag and/or a belt tensioner, should be triggered. Both ignition recommendation CRASH and ignition signals AIR and BELT may also be a more complex signal. Both ignition recommendation CRASH and ignition signal AIR may be, for example, a more complex signal which indicates the degree (e.g. stage 1 or stage 2) to which airbag should be fired. Both ignition recommendation CRASH and ignition signal AIR may additionally include, for example, a crash-severity parameter described in [[DE]] German Published Patent Application No. 100 35 505 [[A1]] or an occupant acceleration or occupant loading. It may be provided that both ignition recommendation CRASH and ignition signals AIR and BELT ~~can~~ may indicate the location and/or the direction of a collision.

Fig. 4 ~~shows~~ illustrates an exemplary embodiment of triggering module 20. Triggering module 20 includes an analog-to-digital converter 25 for sampling acceleration value aS1 and outputting a sampled acceleration value as1, an analog-to-digital converter 26 for sampling acceleration value aS2 and outputting a sampled acceleration value as2, and an analog-to-digital converter 27 for sampling acceleration value aS3 and outputting a sampled acceleration value as3. The sampling frequency of the Δt of analog-to-digital converters 25, 26, and 27 may be, for example, 4 kHz. Triggering module 20 additionally includes (digital) integrators 31, 32, 33, 34, 35, and 36.

Using integrator 31, a pseudospeed value $v0S1$ at time t_0 is ascertained according to

$$v0S1 = \int_{t_0 - \tau_0}^{t_0} as1 \cdot dt$$

5 where τ_0 is the length of a time interval $[t_0 - \tau_0, t_0]$ or 40 (cf. Fig. 5). Time t_0 designates the current time, i.e., the current value of time t .

Using integrator 32, a pseudospeed value $v1S1$ at a time $t_0 - \tau_1$
10 is ascertained according to

$$v1S1 = \int_{t_0 - \tau_0 - \tau_1}^{t_0 - \tau_1} as1 \cdot dt$$

Using integrator 33, a pseudospeed value $v2S1$ at a time $t_0 - \tau_2$ is ascertained according to

$$v2S1 = \int_{t_0 - \tau_0 - \tau_2}^{t_0 - \tau_2} as1 \cdot dt$$

15 Using integrator 34, a pseudospeed value $v3S1$ at a time $t_0 - \tau_3$ is ascertained according to

$$v3S1 = \int_{t_0 - \tau_0 - \tau_3}^{t_0 - \tau_3} as1 \cdot dt$$

20 Using integrator 35, a pseudospeed value $v0S2$ at time t_0 is ascertained according to

$$v0S2 = \int_{t_0 - \tau_0}^{t_0} as2 \cdot dt$$

25 Using integrator 36, a pseudospeed value $v0S3$ at time t_0 is ascertained according to

$$v0S3 = \int_{t_0 - \tau_0}^{t_0} as3 \cdot dt$$

Fig. 5 and Fig. 6 illustrate the effect of integrators 31, 32, 33, 34, 35, and 36. In this context, Fig. 5 ~~shows~~ illustrates an example of a curve of (sampled) acceleration value $as1$ versus time t in the event of a frontal collision of motor vehicle 1 with an obstacle. Fig. 6 ~~shows~~ illustrates an example of a curve of pseudospeed value $v0S1$ for $\tau_0 = 24\text{ms}$.

10 In the exemplary embodiment ~~shown~~ illustrated in Fig. 6, τ_1 is 17 ms, τ_2 is 34 ms, and τ_3 is 51 ms. ~~In one advantageous refinement,~~ τ_1 may be 8 ms, τ_2 may be 16 ms, and τ_3 may be 24 ms.

15 Pseudospeed values $v0S1$, $v1S1$, $v2S1$, $v3S1$, $v0S2$, and $v0S3$ are examples of time averages ~~within the meaning of the present invention.~~

Triggering module 20 further includes a trigger generator 30
20 for generating ignition recommendation CRASH, ~~shown~~ illustrated in more detail in Fig. 7. Trigger generator 30 includes a triggering relationship 30A for generating ignition recommendation CRASH as a function of pseudospeed values $v0S1$, $v1S1$, $v2S1$, $v0S2$, and $v0S3$, a triggering relationship 30B for
25 generating ignition recommendation CRASH as a function of pseudospeed values $v0S1$, $v1S1$, $v2S1$, and $v0S2$, a triggering relationship 30C for generating ignition recommendation CRASH as a function of pseudospeed values $v0S1$, $v1S1$, $v2S1$, and $v0S3$, and a triggering relationship 30D for generating
30 ignition recommendation CRASH as a function of pseudospeed values $v0S1$, $v1S1$, $v2S1$, and $v3S1$.

Trigger generator 30 additionally includes a selection module 38 for selecting a triggering relationship 30A, 30B, 30C, or 30D to use as a current triggering relationship 30E for generating current ignition recommendation CRASH as a function of pseudospeed values v0S1, v1S1, v2S1, v3S1, v0S2, and v0S3. If selection module 38 detects that crash sensor S2 supplies acceleration values aS2 (and therefore that analog-to-digital converter 25 supplies sampled acceleration values as2), and that crash sensor S3 supplies acceleration values as3 (and therefore that analog-to-digital converter 26 supplies sampled acceleration values as3), then selection module 38 selects triggering relationship 30A to use as a current triggering relationship 30E for generating current ignition recommendation CRASH.

If selection module 38 detects that crash sensor S2 supplies acceleration values aS2 (and therefore that analog-to-digital converter 25 supplies sampled acceleration values as2), but that crash sensor S3 does not supply any acceleration values as3 (and therefore that analog-to-digital converter 26 does not supply any sampled acceleration values as3), then selection module 38 selects triggering relationship 30B to use as a current triggering relationship 30E for generating current ignition recommendation CRASH.

If selection module 38 detects that crash sensor S3 supplies acceleration values aS3 (and therefore that analog-to-digital converter 26 supplies sampled acceleration values as3), but that crash sensor S2 does not supply any acceleration values as2 (and therefore that analog-to-digital converter 25 does not supply any sampled acceleration values as2), then selection module 38 selects triggering relationship 30C to use as a current triggering relationship 30E for generating current ignition recommendation CRASH.

If selection module 38 detects that crash sensor S2 does not supply any acceleration values aS2 (and therefore that analog-to-digital converter 25 does not supply any sampled acceleration values as2), and that crash sensor S3 does not supply any acceleration values as3 (and therefore that analog-to-digital converter 26 does not supply any sampled acceleration values as3), then selection module 38 selects triggering relationship 30D to use as a current triggering relationship 30E for generating current ignition recommendation CRASH.

~~In one exemplary embodiment, the~~ **The** selection between triggering relationship 30A, 30B, 30C, or 30D as triggering relationship 30E ~~[[is]]~~ **may be** carried out by selecting between parameters P30A for defining triggering relationship 30A, parameters P30B for defining triggering relationship 30B, parameters P30C for defining triggering relationship 30C, and parameters P30D for defining triggering relationship 30D, to transfer to triggering relationship 30E.

Triggering relationships 30A, 30B, 30C, and 30D (or a part of triggering relationships 30A, 30B, 30C, and 30D) may, for example, take the form of a neural network, as ~~shown~~ **illustrated** in Fig. 8 as an exemplary embodiment for implementing triggering relationship 30A. The neural network ~~shown~~ **illustrated** in Fig. 8 includes five input nodes 50, 51, 52, 53, 54, six covered nodes 60, 61, 62, 63, 64, 65, and an output node 70, each input node 50, 51, 52, 53, 54 being connected to each covered node 60, 61, 62, 63, 64, 65, and each covered node 60, 61, 62, 63, 64, 65 being connected to output node 70. However, for reasons of clarity, Fig. 8 does not ~~show~~ **illustrate** all of the connections between input nodes 50, 51, 52, 53, 54 and covered nodes 60, 61, 62, 63, 64, 65.

Pseudospeed value v0S1 is the input variable input into input node 50, pseudospeed value v1S1 is the input variable input into input node 51, pseudospeed value v2S1 is the input variable input into input node 52, pseudospeed value v0S2 is the input variable input into input node 53, and pseudospeed value v0S3 is the input variable input into input node 54. The output variable from output node 70 is ignition recommendation CRASH.

10 Parameters P3OA, P3OB, P3OC, and P3OD may be, for example, the gains of nodes 50, 51, 52, 53, 54, 60, 61, 62, 63, 64, 65, and 70 of the neural network.

Details regarding neural networks may be found in U.S. Patent No. 5,583,771, U.S. Patent No. 5,684,701, and the documents "Techniques And Application Of Neural Networks", Taylor, M. and Lisboa, Ellis Horwood, West Sussex, England, 1993, "Naturally Intelligent Systems", Caudill, M. and Butler, G., MIT Press, Cambridge, 1990, and "Digital Neural Networks", Kung, S. Y., PTR Prentice Hall, Englewood Cliffs, NJ, 1993, cited in U.S. Patent No. 5,684,701.

Table 1

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/* Evaluation function */
int evaluate_Action(double *x)
{
    int CRASH;

    if (v0S3 <  $\delta_{v0S3}$  ) {
        if (v0S2 <  $\delta_{v0S2}$  ) {
            if (v2S1 <  $\delta_{v2S1}$  ) {
                if (v0S1 <  $\delta_{v0S1}$  ) {
                    CRASH = 0;
                } else {
                    if (v0S3 <  $\delta_{v0S3,2}$  ) {
                        CRASH = 0;
                    } else {
                        if (v0S1 <  $\delta_{v0S1,2}$  ) {
                            if (v1S1 <  $\delta_{v1S1}$  ) {
                                CRASH = 1;
                            } else {
                                CRASH = 0;
                            }
                        } else {
                            CRASH = 1;
                        }
                    }
                }
            }
        } else {
            if (v0S2 <  $\delta_{v0S2,2}$  ) {
                CRASH = 0;
            } else {
                if (v0S3 <  $\delta_{v0S3,3}$  ) {
                    CRASH = 0;
                } else {
                    CRASH = 1;
                }
            }
        }
    } else {
        CRASH = 1;
    }
} else {
    CRASH = 1;
}
return (CRASH);
}

```

As an alternative, triggering relationships 30A, 30B, 30C, and 30D (or a part of triggering relationships 30A, 30B, 30C, and 30D) may be ~~designed~~ arranged, for example, as a sequence of

comparisons to limiting values. Table 1 ~~shows~~ illustrates such a sequence of comparisons to limiting values as an example of a possible implementation of triggering relationship 30A, the code ~~shown~~ illustrated in Table 1 having
5 been automatically generated by a method explained with reference to Fig. 10. For the code ~~shown~~ illustrated in Table 1, t_1 is 4 ms, t_2 is 8 ms, and t_0 is 24 ms. Parameters P30A, P30B, P30C, and P30D may also be, for example, the code ~~shown~~ illustrated in Table 1.

10 Fig. 9 ~~shows~~ illustrates the code of Table 1, represented as a decision tree 80. In this context, reference numeral 81 denotes the inquiry as to whether v_{0S3} is less than a limiting value $\delta_{v_{0S3}}$. Reference numeral 82 denotes the inquiry as to
15 whether v_{0S2} is less than a limiting value $\delta_{v_{0S2}}$. Reference numeral 83 denotes the inquiry as to whether v_{2S1} is less than a limiting value $\delta_{v_{2S1}}$. Reference numeral 84 denotes the inquiry as to whether v_{0S2} is less than a limiting value $\delta_{v_{0S1}}$. Reference numeral 85 denotes the inquiry as to whether v_{0S3} is
20 less than a limiting value $\delta_{v_{0S3},2}$. Reference numeral 86 denotes the inquiry as to whether v_{0S1} is less than a limiting value $\delta_{v_{0S1},2}$. Reference numeral 87 denotes the inquiry as to whether v_{1S1} is less than a limiting value $\delta_{v_{1S1}}$. Reference numeral 88 denotes the inquiry as to whether v_{0S2} is less than
25 a limiting value $\delta_{v_{0S2},2}$. Reference numeral 89 denotes the inquiry as to whether v_{0S3} is less than a limiting value $\delta_{v_{0S3},3}$.

Fig. 10 ~~shows~~ illustrates a method for manufacturing motor
30 vehicle 1. To this end, a test prototype of motor vehicle 1 is initially produced in a step 90, crash sensors corresponding to crash sensors S1, S2, S3 for measuring the motion variable of motor vehicle 1 being installed in the motor vehicle. The test prototype of motor vehicle 1 is
35 subjected to a crash test, where the output signals of the

crash sensors corresponding to crash sensors S1, S2, S3 are measured. A database is constructed from these output signals and the output signals of further crash tests. In this database, pseudospeed values v0S1, v1S1, v2S1, v3S1, v0S2, v0S3 generated from the above-mentioned output signals of the crash sensors corresponding to crash sensors S1, S2, S3 are stored together with a triggering information item CRASHTRUE according to a method ~~described~~ illustrated in Fig. 4, Fig. 16, Fig. 17, and Fig. 18, the triggering information item indicating a setpoint ignition time or a setpoint triggering time. Triggering information item CRASHTRUE may indicate, for example, a setpoint ignition time of airbag 15.

Subsequent to step 90 is a step 91, in which triggering relationships 30A, 30B, 30C und 30D are generated on the basis of the data stored in the database. However, when triggering relationships 30A, 30B, 30C, and 30D are generated, pseudospeed values v0S1, v1S1, v2S1, v3S1, v0S2, and v0S3 are disregarded in a training-suppression time interval around the setpoint triggering time of airbag 15 or belt tensioner 16, in a training-suppression time interval after the setpoint triggering time of airbag 15 or belt tensioner 16, or ~~advantageously, e.g.,~~ in a training-suppression time interval prior to the setpoint triggering time of airbag 15 or belt tensioner 16, as explained below with reference to Fig. 11, Fig. 12, Fig. 13, Fig. 14, and Fig. 15.

Fig. 11 ~~shows~~ illustrates the pseudospeed value according to Fig. 6, along with a corresponding training-suppression time interval t_{hole} , which is prior to a setpoint triggering time of airbag 15 or belt tensioner 16 designated by t_z . In this context, setpoint triggering time t_z ~~is advantageously~~ may be the time by which airbag 15 or belt tensioner 16 should be triggered at the latest. Training-suppression time interval t_{hole} is between 1 ms and 40 ms long, ~~in particular e.g.,~~

between 2 ms and 10 ms long, and advantageously, e.g., approximately 5 ms long. In the present exemplary embodiment, training-suppression time interval t_{hole} is 5 ms.

5 Fig. 12 ~~shows~~ illustrates a section of Fig. 11 for the area between 0 ms and 40 ms. Fig. 13 ~~shows~~ illustrates corresponding triggering information item CRASHTRUE. Triggering information item CRASHTRUE is equal to 0 prior to setpoint triggering time t_z and equal to 1 after setpoint
10 triggering time t_z , but, in the same way manner as the pseudospeed value of Fig. 12, it is disregarded in training-suppression time interval t_{hole} prior to setpoint triggering time t_z for the generation of triggering relationships 30A, 30B, 30C, and 30D. This may be accomplished, for example, by
15 removing the pseudospeed values and triggering information item CRASHTRUE from the data in training-suppression time interval t_{hole} .

Fig. 14 and Fig. 15 ~~show~~ illustrate an alternative procedure,
20 which also disregards the pseudospeed values and triggering information item CRASHTRUE disregarded in training-suppression time interval t_{hole} , when triggering relationships 30A, 30B, 30C, and 30D are generated. In this context, the pseudospeed values are indeed also used in training-suppression time
25 interval t_{hole} prior to setpoint triggering time t_z for generating triggering relationships 30A, 30B, 30C, and 30D, but a variable "no difference" is added to triggering information item CRASHTRUE in training-suppression time interval t_{hole} prior to setpoint triggering time t_z , the
30 variable "no difference" indicating that both a 0 and a 1 outputted by triggering relationships 30A, 30B, 30C, and 30D during a training instance are correct for ignition recommendation CRASH. This means that regardless of whether triggering relationships 30A, 30B, 30C, and 30D output 0 or 1
35 as ignition recommendation CRASH during the training or

learning within training-suppression time interval t_{hole} , it is assumed that the solution is correct, i.e., that ignition recommendation CRASH is equal to triggering information item CRASHTRUE.

5
Using the database data modified according to the procedure described with reference to Fig. 12, Fig. 13, Fig. 14, and Fig. 15, triggering relationships 30A, 30B, 30C, and 30D are ~~then~~ automatically generated with the objective that ignition recommendation CRASH is equal to triggering information item CRASHTRUE for the utilized data. To automatically generate triggering relationships 30A, 30B, 30C, and 30D in an ~~embodiment~~ arrangement as a neural network ~~shown~~ illustrated in Fig. 8, tools conventional for this may be used for
10
15 generating neural networks.

For example, the routine "treefit" from the "Statistics Toolbox" of the program "MATLAB 7" from Mathworks may be used for automatically generating triggering relationships 30A,
20 30B, 30C, and 30D in an ~~embodiment~~ arrangement as a sequence of comparisons represented in Table 1, or in an ~~embodiment~~ arrangement as a decision tree ~~shown~~ illustrated in Fig. 9. This program ~~can~~ may be acquired at the Internet address www.mathworks.com/company/aboutus/contact_us/contact_sales.htm
25 1. Details about the "treefit" routine are ~~shown~~ provided at the Internet address www.mathworks.com/access/helpdesk/help/toolbox/stats/treefit.html.

30 The triggering relationship ~~according to~~ illustrated in Fig. 9 and Table 1 does not take pseudospeed value v_{3S1} into account. It is taken into account in the learning process, but is disregarded during the generation of the code ~~according to~~ illustrated in Table 1.

35

Step 91 is followed by an inquiry 92 as to whether triggering relationships 30A, 30B, 30C, and 30D generated in this manner are correct. To this end, triggering relationships 30A, 30B, and 30D are tested, using the database entries not utilized in
5 step 91. If triggering relationships 30A, 30B, 30C, and 30D are correct, then inquiry 92 is followed by a step 93. Otherwise, step 91 is repeated under different conditions.

In step 93, triggering relationships 30A, 30B, 30C, and 30D
10 are implemented in control unit 2. Control unit 2 is then installed in motor vehicle 1, together with crash sensors S1, S2, and S3 and corresponding occupant protection devices such as airbag 15 or belt tensioner 16.

15 Although explained in connection with a binary triggering information item CRASHTRUE and a binary ignition recommendation CRASH, example embodiments of the present invention is also equally applicable to complex triggering information items and ignition recommendations. This is true
20 for both the procedure described with reference to Fig. 12 and Fig. 13 and the procedure described with reference to Fig. 14 and Fig. 15.

In the preferred exemplary embodiment that is represented,
25 pseudospeed values v0S1, v1S1, v2S1, v3S1, v0S2, and v0S3, i.e., the time averages of (measured) acceleration values aS1, aS2, aS3, are used as input variables and training variables of triggering relationships 30A, 30B, 30C, and 30D. The (measured) acceleration values aS1, aS2, aS3 and sampled
30 acceleration values as1, as2, as3 may be used in the same manner as pseudospeed values v0S1, v1S1, v2S1, v3S1, v0S2, v0S3, as direct and not just indirect input variables and training variables of triggering relationships 30A, 30B, 30C, and 30D. This is also true for both the procedure described
35 with reference to Fig. 12 and Fig. 13 and the procedure

described with reference to Fig. 14 and Fig. 15. In a corresponding modification of the procedure described with reference to Fig. 12 and Fig. 13, (measured) acceleration values $aS1$, $aS2$, $aS3$ and/or scanned acceleration values $as1$, $as2$, $as3$ are removed from the training data of triggering relationships 30A, 30B, 30C, and 30D, in the area of training-suppression time interval τ_{hole} .

Fig. 16 ~~shows~~ illustrates an exemplary embodiment of a triggering module 120 that is an alternative to triggering module 20. In this context, integrators 32, 33, and 34 are replaced by lag elements 132, 133, and 134, which are positioned ~~[[in]] such a manner,~~ that pseudospeed value $v1S1$ results as pseudospeed value $v0S1$ delayed by time τ_1 , pseudospeed value $v2S1$ results as pseudospeed value $v0S1$ delayed by time τ_2 , and pseudospeed value $v3S1$ results as pseudospeed value $v0S1$ delayed by time τ_3 .

One example of a possible (simple) implementation of integrator 31 (that is also appropriately adapted for integrators 32, 33, and 34) is

$$vS1(i) = c \cdot \Delta t \sum_{j=i-\frac{\tau_0}{\Delta t}}^i as1(j)$$

where i is a running index for specifying current time t_0 , and c is a constant. In this case, pseudospeed values $v0S1$, $v1S1$, $v2S1$, and $v3S1$ are yielded, for example, in accordance with the following relationships:

$$v0S1 - vS1(i)$$

$$v1S1 = vS1(i - \frac{\tau_1}{\Delta t})$$

$$v2S1 = vS1(i - \frac{\tau_2}{\Delta t})$$

and

$$v3S1 = vS1(i - \frac{\tau_3}{\Delta t}).$$

Fig. 17 ~~shows~~ illustrates an exemplary embodiment of a triggering module 220 that is an alternative to triggering module 20. In this context, integrators 32, 33, and 34 are replaced by integrators 232, 233, and 234. In this context, pseudospeed value v1S1 is ascertained via integrator 232 according to

$$v1S1 = \int_{t_0 - \tau_1}^{t_0} as1 \cdot dt$$

Using integrator 233, a pseudospeed value v2S1 at time t_0 is ascertained according to

$$v2S1 = \int_{t_0 - \tau_2}^{t_0} as1 \cdot dt$$

Using integrator 234, a pseudospeed value v3S1 at a time t_0 is ascertained according to

$$v3S1 = \int_{t_0 - \tau_3}^{t_0} as1 \cdot dt$$

In triggering module 20 ~~according to~~ illustrated in Fig. 4 and triggering module 120 ~~according to~~ illustrated in Fig. 16, the time intervals differ in their position. However, in triggering module 220 ~~according to~~ illustrated Fig. 17, the time intervals differ in their length. It may also be

provided that time intervals differ in their length and in their position. A corresponding exemplary embodiment is ~~shown~~ illustrated in Fig. 18. Fig. 18 ~~shows~~ illustrates an exemplary embodiment of a triggering module 320 that is an alternative to triggering module 220. In this context, integrator 234 is replaced by an integrator 334, with the aid of which a pseudospeed value v_{3S1} at a time $t_0 - \tau_4$ is ascertained according to

$$v_{3S1} = \int_{t_0 - \tau_3 - \tau_4}^{t_0 - \tau_4} a_{S1} \cdot dt$$

~~The present invention produces~~ According to the foregoing, particularly robust triggering of airbags and belt tensioners may be provided.

Although explained in the exemplary embodiments with regard to airbags and belt tensioners for a frontal collision, example embodiments of the present invention should not, of course, be considered to be restricted to this case. The Example embodiments of the present invention ~~[[is]]~~ are also applicable to side airbags and other occupant protection systems. In one implementation for side airbags, crash sensors S2 and S3 may be ~~situated~~ arranged, for example, in the B-pillar. It may be provided that at least one pseudospeed value over at least one additional time interval be calculated for crash sensor S2 and/or crash sensor S3, as well.

Control unit 2 may also be a distributed system. A control unit within the ~~meaning of the present invention~~ present context does not have to be accommodated in a single housing. A control unit within the ~~meaning of the present invention~~ present context may also be an individual chip or a printed circuit board.

To the extent that decision trees are mentioned in connection with the generation of ignition recommendation CRASH, these may also be replaced by regression trees, association tables, rule sets, supervector machines, or other machine-learning procedures, etc.

Instead of motion variables or their average values, differences of motion variables, average values of these differences, and/or differences of average values may also be used. Thus, e.g., a subtractor may be provided in front of integrators 31, 32, 33, 34, 35, 36, 232, 233, 234, and 334 illustrated in Fig. 4, Fig. 16, Fig. 17, and/or Fig. 18, so that instead of sampled acceleration values $as1$, $as2$, $as3$, differential values $\Delta as1$, $\Delta as2$, $\Delta as3$ are input variables of integrators 31, 32, 33, 34, 35, 36, 232, 233, 234, and 334; $\Delta as1$ being equal to difference $as1-as2$, $\Delta as2$ being equal to difference $as1-as3$, and $\Delta as3$ being equal to difference $as2-as3$. In addition, it may be provided that differential value $\Delta as1$ be processed in the same manner as sampled acceleration value $as1$ illustrated in Fig. 4, Fig. 16, Fig. 17, and/or Fig. 18, that differential value $\Delta as2$ be processed in the same manner as sampled acceleration value $as1$ illustrated in Fig. 4, Fig. 16, Fig. 17, and/or Fig. 18, and/or that differential value $\Delta as3$ be processed in the same manner as sampled acceleration value $as2$ illustrated in Fig. 4, Fig. 16, Fig. 17, and/or Fig. 18. In this case, the number of integrators and the number of input variables are to be appropriately adapted to trigger generator 30.

Differences may also be time differences. Thus, it may be provided that differential values $\Delta as1$, $\Delta as2$, $\Delta as3$ be used in place of sampled acceleration values $as1$, $as2$, $as3$ as input variables of integrators 31, 32, 33, 34, 35, 36, 232, 233, 234, and 334, $\Delta as1(t)$ being equal to difference

as1(t)-as1(t-τ), Δas2 being equal to difference
as2(t)-as2(t-τ) or to difference as2(t)-as3(t-τ), and Δas3
being equal to difference as3(t)-as3(t-τ) or to difference
as3(t)-as2(t-τ).

5

In accordance with above-mentioned variants with regard to the
calculation of a difference, motion variables within the
~~meaning of the present invention~~ **present context** may also be
differences of motion variables, when they are used as input
10 variables.

One may proceed in an analogous manner with pseudospeed values
v0S1, v1S1, v2S1, v3S1, v0S2, and v0S3. Accordingly, average
values of motion variables within the ~~meaning of the present~~
15 ~~invention~~ **present** may also be differences of average values of
motion variables or average values of differences of motion
variables, when they are used as input variables.

~~List of Reference Numerals~~

LIST OF REFERENCE NUMERALS

	1	motor vehicle
	2	control unit
5	3	crash zone
	4	safety zone
	5, 6	leads
	7, 8	dotted line
	10	control module
10	11	belt sensor
	12	seat-occupancy sensor
	14	control element
	15	airbag
	16	belt tensioner
15	20, 120, 220, 320	triggering module
	21	firing table
	25, 26, 27	analog-to-digital converter
	30	trigger generator
	30A, 30B, 30C,	
20	30D, 30E	triggering relationship
	31, 32, 33, 34,	
	35, 36, 232, 233,	
	234, 334	integrator
	38	selection module
25	40	time interval
	50, 51, 52, 53,	
	54	input node
	60, 61, 62, 63,	
	64, 65	covered node
30	70	output node
	80	decision tree
	81, 82, 83, 84,	
	85, 86, 87, 88,	
	89, 92	inquiry
35	90, 91, 93	step

	132, 133, 134	lag element
	AIR, BELT	ignition signal
	aS1, aS2, aS3,	
	as1, as2, as3,	acceleration value
5	CRASH	ignition recommendation
	CRASHTRUE	triggering information item
	ONOFF	switching signal
	MBELT	belt information item
	MSEAT	seat-occupancy information item
10	P30A, P30B,	
	P30C, P30D	parameter
	S1, S2, S3	crash sensor
	t	time
	t_0	current time
15	t_z	setpoint triggering time
	v0S1, v1S1 v2S1,	
	v3S1 v0S2, v0S3	pseudospeed value
	τ_0	length of a time interval
	$\tau_0, \tau_1, \tau_2, \tau_3$	length of a time interval or time (delay)
20	τ_{hole}	training-suppression time interval

Abstract

ABSTRACT

The invention relates to a A motor vehicle ~~(1)~~ having includes at least one first crash sensor ~~(S1)~~ for measuring a motion variable of the motor vehicle ~~(1)~~, situated arranged in a safety zone ~~(4)~~ of the motor vehicle ~~(1)~~, and having at least one second crash sensor ~~(S2)~~ for measuring a motion variable ~~(aS2)~~, situated arranged in a crash zone ~~(3)~~ of the motor vehicle ~~(1)~~, the motor vehicle ~~(1)~~ including an ignition protection device ~~(15, 16)~~ controllable via an ignition signal ~~(CRASH, AIR, BELT)~~ and a control unit ~~(2)~~ for ascertaining the ignition signal ~~(CRASH, AIR, BELT)~~ as a function of the measured motion variables ~~(aS1, aS2)~~ or, in each instance, as a function of a time average ~~(v0S1, v0S2)~~ of the measured motion variables ~~(aS1, aS2)~~ over at least one first time interval ~~([t₀ - t₀, t₀])~~.